Stochastic Euler-Poincaré reduction.

Marc Arnaudon

Université de Bordeaux, France

GSI, École Polytechnique, 29 October 2015



- Arnaudon, Marc; Chen, Xin; Cruzeiro, Ana Bela; Stochastic Euler-Poincaré reduction. J. Math. Phys. 55 (2014), no. 8, 17pp
- Chen, Xin; Cruzeiro, Ana Bela; Ratiu, Tudor S.; Constrained and stochastic variational principles for dissipative equations with advected quantities. arXiv:1506.05024

Deterministic framework

- Euler-Poincaré equations
- Diffeomorphism group on a compact Riemannian manifold
- Volume preserving diffeomorphism group
- Lagrangian paths
- Characterization of the geodesics on $(G_V^s, \langle \cdot, \cdot \rangle^0)$
- Euler-Poincaré equation on G^s_V

2 Stochastic framework

- Semi-martingales in a Lie group
- Stochastic Euler-Poincaré reduction
- Group of volume preserving diffeomorphisms
- Navier-Stokes and Camassa-Holm equations

 $\begin{array}{l} \textbf{Euler-Poincaré equations} \\ \text{Diffeomorphism group on a compact Riemannian manifold} \\ \text{Volume preserving diffeomorphism group} \\ \text{Lagrangian paths} \\ \text{Characterization of the geodesics on } \left(G_V^{S}, \left\langle \cdot, \cdot \right\rangle^{0}\right) \\ \text{Euler-Poincaré equation on } G_V^{S} \end{array}$

< □ > < 同 > < 回 > < 回 > .

• Let *M* be a Riemannian manifold and $L: TM \times [0, T] \rightarrow \mathbb{R}$ a Lagrangian on *M*.

- Let $q \in C^1_{a,b}([0,T];M) := \{q \in C^1([0,T],M), q(0) = a, q(T) = b\}.$
- The action functional $\mathscr{C} : C^1_{a,b}([0,T];M) \to \mathbb{R}$ is defined by

$$\mathscr{C}(q(\cdot)) := \int_0^T L(q(t), \dot{q}(t), t) dt.$$

$$\frac{d}{dt}\left(\frac{\partial L}{\partial \dot{q}}\right) - \frac{\partial L}{\partial q} = 0.$$

 $\begin{array}{l} \textbf{Euler-Poincaré equations} \\ \text{Diffeomorphism group on a compact Riemannian manifold} \\ \text{Volume preserving diffeomorphism group} \\ \text{Lagrangian paths} \\ \text{Characterization of the geodesics on } \left(G_V^S, \left\langle \cdot, \cdot \right\rangle^0\right) \\ \text{Euler-Poincaré equation on } G_V^S \end{array} \right.$

- Let *M* be a Riemannian manifold and *L* : *TM* × [0, *T*] → ℝ a Lagrangian on *M*.
 Let *q* ∈ *C*¹_{*a*,*b*}([0, *T*]; *M*) := {*q* ∈ *C*¹([0, *T*], *M*), *q*(0) = *a*, *q*(*T*) = *b*}.
- The action functional $\mathscr{C} : C^1_{a,b}([0,T];M) \to \mathbb{R}$ is defined by

$$\mathscr{C}(q(\cdot)) := \int_0^T L(q(t), \dot{q}(t), t) dt.$$

$$\frac{d}{dt}\left(\frac{\partial L}{\partial \dot{q}}\right) - \frac{\partial L}{\partial q} = 0.$$

 $\begin{array}{l} \textbf{Euler-Poincaré equations} \\ \text{Diffeomorphism group on a compact Riemannian manifold} \\ \text{Volume preserving diffeomorphism group} \\ \text{Lagrangian paths} \\ \text{Characterization of the geodesics on } \left(G_{V}^{s}, \left\langle \cdot, \cdot, \right\rangle^{0}\right) \\ \text{Euler-Poincaré equation on } G_{V}^{s} \end{array}$

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

- Let *M* be a Riemannian manifold and $L: TM \times [0, T] \rightarrow \mathbb{R}$ a Lagrangian on *M*.
- Let $q \in C^1_{a,b}([0,T];M) := \{q \in C^1([0,T],M), q(0) = a, q(T) = b\}.$
- The action functional $\mathscr{C} : C^1_{a,b}([0, T]; M) \to \mathbb{R}$ is defined by

$$\mathscr{C}(q(\cdot)) := \int_0^T L(q(t), \dot{q}(t), t) dt.$$

$$\frac{d}{dt}\left(\frac{\partial L}{\partial \dot{q}}\right) - \frac{\partial L}{\partial q} = 0.$$

 $\begin{array}{l} \textbf{Euler-Poincaré equations} \\ \text{Diffeomorphism group on a compact Riemannian manifold} \\ \text{Volume preserving diffeomorphism group} \\ \text{Lagrangian paths} \\ \text{Characterization of the geodesics on } \left(G_{V}^{s}, \left\langle \cdot, \cdot, \right\rangle^{0}\right) \\ \text{Euler-Poincaré equation on } G_{V}^{s} \end{array}$

- Let *M* be a Riemannian manifold and $L: TM \times [0, T] \rightarrow \mathbb{R}$ a Lagrangian on *M*.
- Let $q \in C^1_{a,b}([0,T];M) := \{q \in C^1([0,T],M), q(0) = a, q(T) = b\}.$
- The action functional $\mathscr{C}: C^1_{a,b}([0,T];M) \to \mathbb{R}$ is defined by

$$\mathscr{C}(q(\cdot)) := \int_0^T L(q(t), \dot{q}(t), t) dt.$$

$$\frac{d}{dt}\left(\frac{\partial L}{\partial \dot{q}}\right) - \frac{\partial L}{\partial q} = 0.$$



• Suppose that the configuration space M = G is a Lie group and $L: TG \rightarrow \mathbb{R}$ is a left invariant Lagrangian:

$$\ell(\xi) := L(e,\xi) = L(g,g \cdot \xi), \ \forall \xi \in T_eG, \ g \in G.$$

(here and in the sequel, $g \cdot \xi = T_e L_g \xi$)

• The action functional $\mathscr{C}: C^1_{a,b}([0,T];G) \to \mathbb{R}$ is defined by

$$\mathscr{C}(g(\cdot)) := \int_0^T L(g(t), \dot{g}(t)) dt = \int_0^T \ell(\xi(t)) dt$$

where $\xi(t) := g(t)^{-1} \cdot \dot{g}(t)$.

● **[J.E. Marsden, T. Ratiu 1994] [J.E. Marsden, J. Scheurle 1993]**: *g*(·) is a critical point for *C* if and only if it satisfies the Euler-Poincaré equation on *T*^{*}_e*G*

$$\frac{d}{dt}\left(\frac{d\ell}{d\xi}\right) - \operatorname{ad}_{\xi(t)}^*\left(\frac{d\ell}{d\xi}\right) = 0,$$

where $\operatorname{ad}_{\mathcal{E}}^* : T_e^*G \to T_e^*G$ is the dual action of $\operatorname{ad}_{\mathcal{E}} : T_eG \to T_eG$:

$$\langle \operatorname{ad}_{\xi}^* \eta, \theta \rangle = \langle \eta, \operatorname{ad}_{\xi} \theta \rangle, \quad \eta \in T_{\theta}^* G, \quad \theta \in T_{\theta} G.$$



• Suppose that the configuration space M = G is a Lie group and $L: TG \rightarrow \mathbb{R}$ is a left invariant Lagrangian:

$$\ell(\xi) := L(e,\xi) = L(g,g \cdot \xi), \ \forall \xi \in T_eG, \ g \in G.$$

(here and in the sequel, $g \cdot \xi = T_e L_g \xi$)

• The action functional $\mathscr{C}: C^1_{a,b}([0,T];G) \to \mathbb{R}$ is defined by

$$\mathscr{C}(g(\cdot)) := \int_0^T L(g(t), \dot{g}(t)) dt = \int_0^T \ell(\xi(t)) dt,$$

where $\xi(t) := g(t)^{-1} \cdot \dot{g}(t)$.

● **[J.E. Marsden, T. Ratiu 1994] [J.E. Marsden, J. Scheurle 1993]**: *g*(·) is a critical point for *C* if and only if it satisfies the Euler-Poincaré equation on *T*^{*}_e*G*

$$\frac{d}{dt}\left(\frac{d\ell}{d\xi}\right) - \operatorname{ad}_{\xi(t)}^*\left(\frac{d\ell}{d\xi}\right) = 0,$$

where $\operatorname{ad}_{\mathcal{E}}^* : T_e^*G \to T_e^*G$ is the dual action of $\operatorname{ad}_{\mathcal{E}} : T_eG \to T_eG$:

$$\langle \operatorname{ad}_{\xi}^* \eta, \theta \rangle = \langle \eta, \operatorname{ad}_{\xi} \theta \rangle, \quad \eta \in T_{\theta}^* G, \quad \theta \in T_{\theta} G.$$



• Suppose that the configuration space M = G is a Lie group and $L: TG \rightarrow \mathbb{R}$ is a left invariant Lagrangian:

$$\ell(\xi) := L(e,\xi) = L(g,g \cdot \xi), \ \forall \xi \in T_eG, \ g \in G.$$

(here and in the sequel, $g \cdot \xi = T_e L_g \xi$)

• The action functional $\mathscr{C}: C^1_{a,b}([0,T];G) \to \mathbb{R}$ is defined by

$$\mathscr{C}(g(\cdot)) := \int_0^T L(g(t), \dot{g}(t)) dt = \int_0^T \ell(\xi(t)) dt,$$

where $\xi(t) := g(t)^{-1} \cdot \dot{g}(t)$.

• [J.E. Marsden, T. Ratiu 1994] [J.E. Marsden, J. Scheurle 1993]: $g(\cdot)$ is a critical point for \mathscr{C} if and only if it satisfies the Euler-Poincaré equation on T_e^*G

$$\frac{d}{dt}\left(\frac{d\ell}{d\xi}\right) - \operatorname{ad}_{\xi(t)}^{*}\left(\frac{d\ell}{d\xi}\right) = 0,$$

where $\operatorname{ad}_{\xi}^*: T_e^*G \to T_e^*G$ is the dual action of $\operatorname{ad}_{\xi}: T_eG \to T_eG$:

$$\langle \operatorname{ad}_{\xi}^* \eta, \theta \rangle = \langle \eta, \operatorname{ad}_{\xi} \theta \rangle, \quad \eta \in T_{\theta}^* G, \quad \theta \in T_{\theta} G.$$

• We will be interested in variations $\xi(\cdot)$ satisfying

$\dot{\xi}(t)=\dot{ u}(t)+\operatorname{ad}_{\xi(t)} u(t) \hspace{0.1in} ext{for some} \hspace{0.1in} u\in C^{1}([0,T], \hspace{0.1in} T_{e}G),$

which is equivalent to the variation of $g(\cdot)$ with the perturbation $g^{\varepsilon}(t) = g(t)e_{\varepsilon,\nu}(t)$, where $e_{\varepsilon,\nu}(t)$ is the unique solution to the following ODE on G:

$$\begin{cases} \frac{d}{dt}e_{\varepsilon,\nu}(t) = \varepsilon e_{\varepsilon,\nu}(t) \cdot \dot{\nu}(t),\\ e_{\varepsilon,\nu}(0) = e. \end{cases}$$

< ロ > < 同 > < 三 > < 三 > -

• We will be interested in variations $\xi(\cdot)$ satisfying

$$\dot{\xi}(t) = \dot{
u}(t) + \operatorname{ad}_{\xi(t)}
u(t) \quad ext{for some} \quad
u \in C^1([0, T], \ T_e G),$$

which is equivalent to the variation of $g(\cdot)$ with the perturbation $g^{\varepsilon}(t) = g(t)e_{\varepsilon,\nu}(t)$, where $e_{\varepsilon,\nu}(t)$ is the unique solution to the following ODE on G:

$$\begin{cases} \frac{d}{dt} \boldsymbol{e}_{\varepsilon,\nu}(t) = \varepsilon \boldsymbol{e}_{\varepsilon,\nu}(t) \cdot \dot{\nu}(t), \\ \boldsymbol{e}_{\varepsilon,\nu}(0) = \boldsymbol{e}. \end{cases}$$

Euler-Poincaré equations Diffeomorphism group on a compact Riemannian manifold Volume preserving diffeomorphism group Lagrangian paths Characterization of the geodesics on $\left(G_{V}^{S}, \langle \cdot, \cdot \rangle^{0}\right)$ Euler-Poincaré equation on G_{V}^{S}

< ロ > < 同 > < 回 > < 回 >

• Let M be a n-dimensional compact Riemannian manifold. We define

$$G^s := \left\{ g: M o M ext{ a bijection }, g, g^{-1} \in H^s(M,M)
ight\},$$

where $H^{s}(M, M)$ denotes the manifold of Sobolev maps of class $s > 1 + \frac{\pi}{2}$ from *M* to itself.

- If $s > 1 + \frac{n}{2}$ then G^s is a C^{∞} Hilbert manifold.
- *G^s* is a group under composition between maps, right translation is smooth, left translation and inversion are only continuous. *G^s* is also a topological group (but not an infinite dimensional Lie group).

Euler-Poincaré equations Diffeomorphism group on a compact Riemannian manifold Volume preserving diffeomorphism group Lagrangian paths Characterization of the geodesics on $\left(G_{V}^{S}, \langle \cdot, \cdot \rangle^{0}\right)$ Euler-Poincaré equation on G_{V}^{S}

イロト イ団ト イヨト イヨ

• Let M be a n-dimensional compact Riemannian manifold. We define

$$G^s := \left\{ g: M o M ext{ a bijection }, g, g^{-1} \in H^s(M,M)
ight\},$$

where $H^{s}(M, M)$ denotes the manifold of Sobolev maps of class $s > 1 + \frac{\pi}{2}$ from M to itself.

- If $s > 1 + \frac{n}{2}$ then G^s is a C^{∞} Hilbert manifold.
- *G^s* is a group under composition between maps, right translation is smooth, left translation and inversion are only continuous. *G^s* is also a topological group (but not an infinite dimensional Lie group).

Euler-Poincaré equations Diffeomorphism group on a compact Riemannian manifold Volume preserving diffeomorphism group Lagrangian paths Characterization of the geodesics on $\left(G_{V}^{s}, \left\langle \cdot, \cdot \right\rangle^{0}\right)$ Euler-Poincaré equation on G_{V}^{s}

• Let M be a n-dimensional compact Riemannian manifold. We define

$$G^{s}:=\left\{g:M
ightarrow M$$
 a bijection $,g,g^{-1}\in H^{s}(M,M)
ight\},$

where $H^{s}(M, M)$ denotes the manifold of Sobolev maps of class $s > 1 + \frac{\pi}{2}$ from M to itself.

- If $s > 1 + \frac{n}{2}$ then G^s is a C^{∞} Hilbert manifold.
- *G^s* is a group under composition between maps, right translation is smooth, left translation and inversion are only continuous. *G^s* is also a topological group (but not an infinite dimensional Lie group).

Euler-Poincaré equations Diffeomorphism group on a compact Riemannian manifold Volume preserving diffeomorphism group Lagrangian paths Characterization of the geodesics on $\left(G_V^S, \langle \cdot, \cdot \rangle^0\right)$ Euler-Poincaré equation on G_V^S

• The tangent space $T_{\eta}G^{s}$ at arbitrary $\eta \in G^{s}$ is

 $T_{\eta}G^{s} = \left\{ U: M \to TM \text{ of class } H^{s}, \ U(m) \in T_{\eta(m)}M \right\}.$

• The Riemannian structure on *M* induces the weak L^2 , or hydrodynamic, metric $\langle \cdot, \cdot \rangle^0$ on G^s given by

$$\langle U, V \rangle_{\eta}^{0} := \int_{M} \langle U_{\eta}(m), V_{\eta}(m) \rangle_{m} d\mu_{g}(m),$$

for any $\eta \in G^s$, $U, V \in T_{\eta}G^s$. Here $U_{\eta} := U \circ \eta^{-1} \in T_eG^s$ and μ_g denotes the Riemannian volume asociated with (M, g).

• Obviously, $\langle \cdot, \cdot \rangle^0$ is a right invariant metric on G^s .

Diffeomorphism group on a compact Riemannian manifold

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

• The tangent space $T_n G^s$ at arbitrary $\eta \in G^s$ is

$$T_{\eta}G^{s} = \left\{ U: M
ightarrow TM ext{ of class } H^{s}, \ U(m) \in T_{\eta(m)}M
ight\}.$$

• The Riemannian structure on M induces the weak L^2 , or hydrodynamic, metric $\langle \cdot, \cdot \rangle^0$ on G^s given by

$$\langle U, V \rangle_{\eta}^{0} := \int_{M} \langle U_{\eta}(m), V_{\eta}(m) \rangle_{m} d\mu_{g}(m),$$

for any $\eta \in G^s$, $U, V \in T_n G^s$. Here $U_n := U \circ \eta^{-1} \in T_e G^s$ and μ_q denotes the Riemannian volume associated with (M, g).

• Obviously, $\langle \cdot, \cdot \rangle^0$ is a right invariant metric on G^s .

Euler-Poincaré equations Diffeomorphism group on a compact Riemannian manifold Volume preserving diffeomorphism group Lagrangian paths Characterization of the geodesics on $\left(G_V^S, \langle \cdot, \cdot, \rangle^0\right)$ Euler-Poincaré equation on G_V^S

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

• The tangent space $T_{\eta}G^{s}$ at arbitrary $\eta \in G^{s}$ is

$$T_{\eta}G^{s} = \left\{ U: M
ightarrow TM ext{ of class } H^{s}, \ U(m) \in T_{\eta(m)}M
ight\}.$$

• The Riemannian structure on *M* induces the weak L^2 , or hydrodynamic, metric $\langle \cdot, \cdot \rangle^0$ on G^s given by

$$\langle U, V \rangle_{\eta}^{0} := \int_{M} \langle U_{\eta}(m), V_{\eta}(m) \rangle_{m} d\mu_{g}(m),$$

for any $\eta \in G^s$, $U, V \in T_{\eta}G^s$. Here $U_{\eta} := U \circ \eta^{-1} \in T_eG^s$ and μ_g denotes the Riemannian volume asociated with (M, g).

• Obviously, $\langle \cdot, \cdot \rangle^0$ is a right invariant metric on G^s .



 Let
 ∇ be the Levi-Civita connection associated with the Riemannian manifold (M, g). We define a right invariant connection
 ∇⁰ on G^s by

$$\left(\nabla_{\tilde{X}}^{0}\tilde{Y}\right)(\eta):=\frac{\partial}{\partial t}\Big|_{t=0}\left(\tilde{Y}(\eta_{t})\circ\eta_{t}^{-1}\right)\circ\eta+\left(\nabla_{X_{\eta}}Y_{\eta}\right)\circ\eta,$$

where $\tilde{X}, \tilde{Y} \in \mathscr{L}(G^s), X_{\eta} := \tilde{X} \circ \eta^{-1}, Y_{\eta} := \tilde{Y} \circ \eta^{-1} \in \mathscr{L}^s(M)$, and η is a C^1 curve in G^s such that $\eta_0 = \eta$ and $\frac{d}{dt}\Big|_{t=0} \eta_t = \tilde{X}(\eta)$. Here $\mathscr{L}(G^s)$ denotes the set of smooth vector fields on G^s .

• ∇^0 is the Levi-Civita connection associated to $(G^s, \langle \cdot, \cdot \rangle^0)$.

イロト イ団ト イヨト イヨト

 Let
 ∇ be the Levi-Civita connection associated with the Riemannian manifold (M, g). We define a right invariant connection
 ∇⁰ on G^s by

$$\left(\nabla_{\tilde{X}}^{0}\tilde{Y}\right)(\eta):=\frac{\partial}{\partial t}\Big|_{t=0}\left(\tilde{Y}(\eta_{t})\circ\eta_{t}^{-1}\right)\circ\eta+\left(\nabla_{X_{\eta}}Y_{\eta}\right)\circ\eta,$$

where $\tilde{X}, \tilde{Y} \in \mathscr{L}(G^s), X_{\eta} := \tilde{X} \circ \eta^{-1}, Y_{\eta} := \tilde{Y} \circ \eta^{-1} \in \mathscr{L}^s(M)$, and η is a C^1 curve in G^s such that $\eta_0 = \eta$ and $\frac{d}{dt}\Big|_{t=0} \eta_t = \tilde{X}(\eta)$. Here $\mathscr{L}(G^s)$ denotes the set of smooth vector fields on G^s .

• ∇^0 is the Levi-Civita connection associated to $(G^s, \langle \cdot, \cdot \rangle^0)$.

< ロ > < 同 > < 回 > < 回 >



$G_V^{s}:=\left\{g,g\in G^{s},\;g ext{ is volume preserving} ight\}.$

- G_V^s is still a topological group.
- The tangent space $T_e G_V^s$ is

$$\mathscr{G}_V^s = T_e G_V^s = \left\{ U, \ U \in T_e G^s, \ \operatorname{div}(U) = 0 \right\}.$$

• The L^2 -metric $\langle \cdot, \cdot \rangle^0$ and its Levi-Civita connection $\nabla^{0,V}$ are defined on G_V^s by orthogonal projection. More precisely the Levi Civita connection on G_V^s is given by $\nabla_X^{0,V} Y = P_{\theta}(\nabla_X^0 Y)$ with P_{θ} the orthogonal projection on \mathscr{G}_V^s :

$$H^{s}(TM) = \mathscr{G}_{V}^{s} \oplus dH^{s+1}(M).$$



 $G_V^s := \left\{ g, g \in G^s, \; g \; ext{is volume preserving}
ight\}.$

• G_V^s is still a topological group.

• The tangent space $T_e G_V^s$ is

$$\mathscr{G}_V^s = T_e G_V^s = \left\{ U, \ U \in T_e G^s, \ \operatorname{div}(U) = 0 \right\}.$$

• The L^2 -metric $\langle \cdot, \cdot \rangle^0$ and its Levi-Civita connection $\nabla^{0,V}$ are defined on G_V^s by orthogonal projection. More precisely the Levi Civita connection on G_V^s is given by $\nabla_X^{0,V} Y = P_{\theta}(\nabla_X^0 Y)$ with P_{θ} the orthogonal projection on \mathscr{G}_V^s :

$$H^{s}(TM) = \mathscr{G}_{V}^{s} \oplus dH^{s+1}(M).$$



 $G_V^s := \{g, g \in G^s, \ g \text{ is volume preserving}\}.$

- G_V^s is still a topological group.
- The tangent space $T_e G_V^s$ is

$$\mathscr{G}_V^s = T_e G_V^s = \left\{ U, \ U \in T_e G^s, \ \operatorname{div}(U) = 0 \right\}.$$

The L²-metric ⟨·, ·⟩⁰ and its Levi-Civita connection ∇^{0, V} are defined on G^s_V by orthogonal projection. More precisely the Levi Civita connection on G^s_V is given by ∇^{0, V}_X Y = P_θ(∇⁰_X Y) with P_θ the orthogonal projection on 𝒢^s_V:

$$H^{s}(TM) = \mathscr{G}^{s}_{V} \oplus dH^{s+1}(M).$$



 $G_V^s := \{g, g \in G^s, \ g \text{ is volume preserving}\}.$

- G_V^s is still a topological group.
- The tangent space $T_e G_V^s$ is

$$\mathscr{G}_V^s = T_e G_V^s = \left\{ U, \ U \in T_e G^s, \ \operatorname{div}(U) = 0 \right\}.$$

• The L^2 -metric $\langle \cdot, \cdot \rangle^0$ and its Levi-Civita connection $\nabla^{0,V}$ are defined on G^s_V by orthogonal projection. More precisely the Levi Civita connection on G^s_V is given by $\nabla^{0,V}_X Y = P_e(\nabla^0_X Y)$ with P_e the orthogonal projection on \mathscr{G}^s_V :

$$H^{s}(TM) = \mathscr{G}^{s}_{V} \oplus dH^{s+1}(M).$$



• Consider the ODE on M

$$\begin{cases} \frac{d}{dt} (g_t(x)) &= u(t, g_t(x)) \\ g_0(x) &= x. \end{cases}$$

Here $u(t, \cdot) \in T_e G^s$ for every t > 0.

- For every fixed t > 0, $g_t(\cdot) \in G^s(M)$. So $g \in C^1([0, T], G^s)$.
- If div(u(t)) = 0 for every t then $g \in C^1([0, T], G_V^s)$



• Consider the ODE on M

$$\begin{cases} \frac{d}{dt} (g_t(x)) &= u(t, g_t(x)) \\ g_0(x) &= x. \end{cases}$$

Here $u(t, \cdot) \in T_e G^s$ for every t > 0.

• For every fixed t > 0, $g_t(\cdot) \in G^s(M)$. So $g \in C^1([0, T], G^s)$.

• If div(u(t)) = 0 for every t then $g \in C^1([0, T], G_V^s)$



• Consider the ODE on M

$$\begin{cases} \frac{d}{dt} (g_t(x)) &= u(t, g_t(x)) \\ g_0(x) &= x. \end{cases}$$

Here $u(t, \cdot) \in T_e G^s$ for every t > 0.

- For every fixed t > 0, $g_t(\cdot) \in G^s(M)$. So $g \in C^1([0, T], G^s)$.
- If $\operatorname{div}(u(t)) = 0$ for every t then $g \in C^1([0, T], G_V^s)$

< ロ > < 同 > < 回 > < 回 > < 回 > <



• [V.I. Arnold 1966] [D.G. Ebin, J.E. Marsden 1970] A Lagrangian path $g \in C^2([0, T], G_V^s)$ satisfying the equation above is a geodesic on $(G_V^s, \langle \cdot, \cdot \rangle^{0, V})$ (i.e. $\nabla_{\dot{g}(t)}^{0, V} \dot{g}(t)$) if and only of the velocity field *u* satisfies the Euler equation for incompressible inviscid fluids

(E)
$$\begin{cases} \frac{\partial u}{\partial t} = -\nabla_u u - \nabla p \\ \operatorname{div} u = 0 \end{cases}$$

• Notice that the term ∇p corresponds to the use of ∇^0 instead of $\nabla^{0,V}$: the first system rewrites as

$$\begin{array}{ll} \frac{\partial u}{\partial t} &= -\nabla_u^{0, V} u\\ \operatorname{div} u &= 0 \end{array}$$



 [V.I. Arnold 1966] [D.G. Ebin, J.E. Marsden 1970] A Lagrangian path *g* ∈ C²([0, *T*], G^s_V) satisfying the equation above is a geodesic on (G^s_V, ⟨·, ·⟩^{0, V}) (i.e. ∇^{0,V}_{g(t)}g(t)) if and only of the velocity field *u* satisfies the Euler equation for incompressible inviscid fluids

(E)
$$\begin{cases} \frac{\partial u}{\partial t} = -\nabla_u u - \nabla p \\ \operatorname{div} u = 0 \end{cases}$$

 Notice that the term ∇p corresponds to the use of ∇⁰ instead of ∇^{0, V}: the first system rewrites as

$$\begin{cases} \frac{\partial u}{\partial t} &= -\nabla_u^{0, V} u\\ \operatorname{div} u &= 0 \end{cases}$$



• If we take $\ell : T_e G_V^s \to \mathbb{R}$ as

$$\ell(X) := \langle X, X \rangle, \quad X \in T_e G_V^s,$$

and define the action functional $\mathscr{C}: C^1_{e,e}([0,T],G^s_V) \to \mathbb{R}$ by

$$\mathscr{C}(g(\cdot)) := \int_0^T \ell\left(\dot{g}(t) \cdot g(t)^{-1}\right) dt,$$

then a Lagrangian path $g \in C^2([0, T], G^s_V)$ integral path of u is a critical point of \mathscr{C} if and only if u satisfies the Euler equation (E). [J.E. Marsden, T. Ratiu 1994] [J.E. Marsden, J. Scheurle 1993]

• [S. Shkoller 1998] If we take $\ell : T_e G_V^s \to \mathbb{R}$ as the H^1 metric

$$\ell(X) := \int_{M} \langle X, X \rangle_{m} \, d\mu_{g}(m) + \alpha^{2} \int_{M} \langle \nabla X, \nabla X \rangle_{m} \, d\mu_{g}(m), \ X \in T_{e}G_{V}^{s},$$

and define the action functional $\mathscr{C} : C^1_{\theta, \theta}([0, T], G^s_V) \to \mathbb{R}$ in the same way as before, then a Lagrangian path $g \in C^2([0, T], G^s_V)$ integral path of u is a critical point of \mathscr{C} if and only if u satisfies the Camassa-Holm equation

$$\begin{cases} \frac{\partial \nu}{\partial t} + u \cdot \nu + \alpha^2 (\nabla u)^* \cdot \Delta \nu &= \nabla p, \\ \nu &= (1 + \alpha^2 \Delta) u, \\ \operatorname{div}(u) &= 0. \end{cases}$$

< ロ > < 同 > < 回 > < 回 >

Aim: to establish a stochastic Euler-Poincaré reduction theorem in a general Lie group.

To apply it to volume preserving diffeomorphisms of a compact symmetric space. Stochastic term will correspond for Euler equation to introducing viscosity.

Marc Arnaudon Stochastic Euler-Poincaré reduction.

Aim: to establish a stochastic Euler-Poincaré reduction theorem in a general Lie group. To apply it to volume preserving diffeomorphisms of a compact symmetric space. Stochastic term will correspond for Euler equation to introducing viscosity.

Aim: to establish a stochastic Euler-Poincaré reduction theorem in a general Lie group. To apply it to volume preserving diffeomorphisms of a compact symmetric space. Stochastic term will correspond for Euler equation to introducing viscosity.

Semi-martingales in a Lie group Stochastic Euler-Poincaré reduction Group of volume preserving diffeomorphisms Navier-Stokes and Camassa-Holm equations

An \mathbb{R}^n -valued semimartingale ξ_t has a decomposition

$$\xi_t(\omega) = N_t(\omega) + A_t(\omega)$$

where (N_t) is a local martingale and (A_t) has finite variation. If (N_t) is a martingale, then

 $\mathbb{E}[N_t|\mathscr{F}_s]=N_s, \quad t\geq s.$

We are interested in semimartingales which furthermore satisfy

$$A_t(\omega) = \int_0^t a_s(\omega) \, ds$$

Defining

$$\frac{D\xi_t}{dt} := \lim_{\varepsilon \to 0} \mathbb{E}\left[\frac{\xi_{t+\varepsilon} - \xi_t}{\varepsilon} | \mathscr{F}_t\right],$$

we have $\frac{D\xi_t}{dt} = a_t$

Semi-martingales in a Lie group Stochastic Euler-Poincaré reduction Group of volume preserving diffeomorphisms Navier-Stokes and Camassa-Holm equations

An \mathbb{R}^n -valued semimartingale ξ_t has a decomposition

$$\xi_t(\omega) = N_t(\omega) + A_t(\omega)$$

where (N_t) is a local martingale and (A_t) has finite variation. If (N_t) is a martingale, then

$$\mathbb{E}[N_t|\mathscr{F}_s] = N_s, \quad t \ge s.$$

We are interested in semimartingales which furthermore satisfy

$$A_t(\omega) = \int_0^t a_s(\omega) \, ds$$

Defining

$$\frac{D\xi_t}{dt} := \lim_{\varepsilon \to 0} \mathbb{E}\left[\frac{\xi_{t+\varepsilon} - \xi_t}{\varepsilon} | \mathscr{F}_t\right],$$

we have $\frac{D\xi_t}{dt} = a_t$

Semi-martingales in a Lie group Stochastic Euler-Poincaré reduction Group of volume preserving diffeomorphisms Navier-Stokes and Camassa-Holm equations

An \mathbb{R}^n -valued semimartingale ξ_t has a decomposition

$$\xi_t(\omega) = N_t(\omega) + A_t(\omega)$$

where (N_t) is a local martingale and (A_t) has finite variation. If (N_t) is a martingale, then

$$\mathbb{E}[N_t|\mathscr{F}_s] = N_s, \quad t \ge s.$$

We are interested in semimartingales which furthermore satisfy

$$A_t(\omega) = \int_0^t a_s(\omega) \, ds.$$

Defining

$$\frac{D\xi_t}{dt} := \lim_{\varepsilon \to 0} \mathbb{E}\left[\frac{\xi_{t+\varepsilon} - \xi_t}{\varepsilon} | \mathscr{F}_t\right],$$

we have $\frac{D\xi_t}{dt} = a_t$

Itô formula :

$$f(\xi_t) = f(\xi_0) + \int_0^t \langle df(\xi_s), dN_s \rangle + \int_0^t \langle df(\xi_s), dA_s \rangle + \frac{1}{2} \int_0^t \operatorname{Hess} f(d\xi_s \otimes d\xi_s).$$

From this we see that ξ_t is a local martingale if and only if for all $f \in C^2(\mathbb{R}^n)$,

$$f(\xi_t) - f(\xi_0) - \frac{1}{2} \int_0^t \text{Hess}f(d\xi_s \otimes d\xi_s)$$
 is a real valued local martingale.

This property becomes a definition for manifold-valued martingales.

Definition

Let
$$a_t \in T_{\xi_t} M$$
 an adapted process. If for all $f \in C^2(M)$
 $f(\xi_t) - f(\xi_0) - \int_0^t \langle df(\xi_s), a_s \rangle \, ds - \frac{1}{2} \int_0^t \operatorname{Hess} f(d\xi_s \otimes d\xi_s)$ is a real valued local martingale
then $\frac{D\xi_t}{dt} = a_t$.

イロト イヨト イヨト イヨト

Itô formula :

$$f(\xi_t) = f(\xi_0) + \int_0^t \langle df(\xi_s), dN_s \rangle + \int_0^t \langle df(\xi_s), dA_s \rangle + \frac{1}{2} \int_0^t \text{Hess} f(d\xi_s \otimes d\xi_s).$$

From this we see that ξ_t is a local martingale if and only if for all $f \in C^2(\mathbb{R}^n)$,

$$f(\xi_t) - f(\xi_0) - \frac{1}{2} \int_0^t \text{Hess} f(d\xi_s \otimes d\xi_s)$$
 is a real valued local martingale.

This property becomes a definition for manifold-valued martingales.

Definition

Let $a_t \in T_{\xi_t} M$ an adapted process. If for all $f \in C^2(M)$ $f(\xi_t) - f(\xi_0) - \int_0^t \langle df(\xi_s), a_s \rangle \, ds - \frac{1}{2} \int_0^t \text{Hess} f(d\xi_s \otimes d\xi_s)$ is a real valued local martinga then $\frac{D\xi_t}{dt} = a_t$.

< ロ > < 同 > < 回 > < 回 >

Itô formula :

$$f(\xi_t) = f(\xi_0) + \int_0^t \langle df(\xi_s), dN_s \rangle + \int_0^t \langle df(\xi_s), dA_s \rangle + \frac{1}{2} \int_0^t \operatorname{Hess} f(d\xi_s \otimes d\xi_s).$$

From this we see that ξ_t is a local martingale if and only if for all $f \in C^2(\mathbb{R}^n)$,

$$f(\xi_t) - f(\xi_0) - \frac{1}{2} \int_0^t \text{Hess} f(d\xi_s \otimes d\xi_s)$$
 is a real valued local martingale.

This property becomes a definition for manifold-valued martingales.

Definition

Let
$$a_t \in T_{\xi_t} M$$
 an adapted process. If for all $f \in C^2(M)$
 $f(\xi_t) - f(\xi_0) - \int_0^t \langle df(\xi_s), a_s \rangle \, ds - \frac{1}{2} \int_0^t \operatorname{Hess} f(d\xi_s \otimes d\xi_s)$ is a real valued local martingale
then $\frac{D\xi_t}{dt} = a_t$.

Itô formula :

$$f(\xi_t) = f(\xi_0) + \int_0^t \langle df(\xi_s), dN_s \rangle + \int_0^t \langle df(\xi_s), dA_s \rangle + \frac{1}{2} \int_0^t \operatorname{Hess} f(d\xi_s \otimes d\xi_s).$$

From this we see that ξ_t is a local martingale if and only if for all $f \in C^2(\mathbb{R}^n)$,

$$f(\xi_t) - f(\xi_0) - \frac{1}{2} \int_0^t \text{Hess} f(d\xi_s \otimes d\xi_s)$$
 is a real valued local martingale.

This property becomes a definition for manifold-valued martingales.

Definition

Let $a_t \in T_{\xi_t} M$ an adapted process. If for all $f \in C^2(M)$

 $f(\xi_t) - f(\xi_0) - \int_0^t \langle df(\xi_s), a_s \rangle \, ds - \frac{1}{2} \int_0^t \operatorname{Hess} f(d\xi_s \otimes d\xi_s)$ is a real valued local martingale

then $\frac{D\xi_t}{dt} = a_t$.

< ロ > < 同 > < 回 > < 回 >

Semi-martingales in a Lie group Stochastic Euler-Poincaré reduction Group of volume preserving diffeomorphisms Navier-Stokes and Camassa-Holm equations

Let *G* be a Lie group with right invariant metric $\langle \cdot, \cdot \rangle$ and right invariant connection ∇ . Let $\mathscr{G} := T_e G$ be the Lie algebra of *G*.

Consider a countable family H_i , $i \ge 1$, of elements of \mathscr{G} , and $u \in C^1([0, T], \mathscr{G})$. Consider the Stratonovich equation

$$dg_t = \left(\sum_{i \ge 1} H_i \circ dW_t^i - \frac{1}{2} \nabla_{H_i} H_i \, dt + u(t) \, dt\right) \cdot g_t$$

$$g_0 = e$$

where the (W_t^i) are independent real valued Brownian motions. Itô formula writes

$$\begin{split} f(g_t) = & f(g_0) + \sum_{i \ge 1} \int_0^t \langle df(g_s), H_i dW_s^i \rangle + \int_0^t \langle df(g_s), u(s)g_s \, ds \rangle \\ & + \frac{1}{2} \sum_{i \ge 1} \int_0^t \operatorname{Hess} f(H_i(g_s), H_i(g_s)) \, ds. \end{split}$$

This implies that $\frac{Dg_t}{dt} = u(t)g_t$

Particular case

If (H_i) is an orthonormal basis, $\nabla_{H_i}H_i = 0$, ∇ is the Levi Civita connection associated to the metric and $u \equiv 0$, then g_t is a Brownian motion in G.

Let *G* be a Lie group with right invariant metric $\langle \cdot, \cdot \rangle$ and right invariant connection ∇ . Let $\mathscr{G} := T_e G$ be the Lie algebra of *G*. Consider a countable family H_i , $i \ge 1$, of elements of \mathscr{G} , and $u \in C^1([0, T], \mathscr{G})$.

Consider the Stratonovich equation

$$\begin{aligned} dg_t &= \left(\sum_{i \geq 1} H_i \circ dW_t^i - \frac{1}{2} \nabla_{H_i} H_i \, dt + u(t) \, dt \right) \cdot g_t \\ g_0 &= e \end{aligned}$$

where the (W_t^i) are independent real valued Brownian motions. Itô formula writes

$$\begin{split} f(g_t) = &f(g_0) + \sum_{i \ge 1} \int_0^t \langle df(g_s), H_i dW_s^i \rangle + \int_0^t \langle df(g_s), u(s)g_s \, ds \rangle \\ &+ \frac{1}{2} \sum_{i \ge 1} \int_0^t \operatorname{Hess} f(H_i(g_s), H_i(g_s)) \, ds. \end{split}$$

This implies that $rac{Dg_t}{dt} = u(t)g_t$

Particular case

If (H_i) is an orthonormal basis, $\nabla_{H_i}H_i = 0$, ∇ is the Levi Civita connection associated to the metric and $u \equiv 0$, then g_t is a Brownian motion in G.

Let *G* be a Lie group with right invariant metric $\langle \cdot, \cdot \rangle$ and right invariant connection ∇ . Let $\mathscr{G} := T_{\theta}G$ be the Lie algebra of *G*.

Consider a countable family H_i , $i \ge 1$, of elements of \mathscr{G} , and $u \in C^1([0, T], \mathscr{G})$. Consider the Stratonovich equation

$$dg_t = \left(\sum_{i\geq 1} H_i \circ dW_t^i - \frac{1}{2} \nabla_{H_i} H_i \, dt + u(t) \, dt\right) \cdot g_t$$

$$g_0 = e$$

where the (W_t^i) are independent real valued Brownian motions. Itô formula writes

$$f(g_t) = f(g_0) + \sum_{i \ge 1} \int_0^t \langle df(g_s), H_i dW_s^i \rangle + \int_0^t \langle df(g_s), u(s)g_s ds \rangle + \frac{1}{2} \sum_{i \ge 1} \int_0^t \operatorname{Hess} f(H_i(g_s), H_i(g_s)) ds.$$

This implies that $\frac{Dg_t}{dt} = u(t)g_t$.

Particular case

If (*H_i*) is an orthonormal basis, $\nabla_{H_i}H_i = 0$, ∇ is the Levi Civita connection associated to the metric and $u \equiv 0$, then g_t is a Brownian motion in *G*.

Semi-martingales in a Lie group Stochastic Euler-Poincaré reduction Group of volume preserving diffeomorphisms Navier-Stokes and Camassa-Holm equations

On the space $\mathcal{S}(G)$ of G-valued semimartingales define

$$J(\xi) = \frac{1}{2} \mathbb{E} \left[\int_0^T \left\| \frac{D\xi}{dt} \right\|^2 dt \right].$$

Perturbation: for $v \in C^1([0, T], \mathscr{G})$ satisfying v(0) = v(T) = 0 and $\varepsilon > 0$, let $e_{\varepsilon, v}(\cdot) \in C^1([0, T], G)$ the flow generated by εv :

$$\begin{cases} \frac{d}{dt} e_{\varepsilon,v}(t) &= \varepsilon \dot{v}(t) \cdot e_{\varepsilon,v}(t) \\ e_{\varepsilon,v}(0) &= e \end{cases}$$

Definition

We say that $g \in \mathscr{S}(G)$ is a critical point of J if for all $v \in C^1([0, T], \mathscr{G})$ satisfying v(0) = v(T) = 0,

$$rac{dJ}{darepsilon}igert_{arepsilon=0}g_{arepsilon,v}=0$$
 where $g_{arepsilon,v}(t)=e_{arepsilon,v}(t)g(t).$

On the space $\mathscr{S}(G)$ of G-valued semimartingales define

$$J(\xi) = \frac{1}{2} \mathbb{E} \left[\int_0^T \left\| \frac{D\xi}{dt} \right\|^2 dt \right].$$

Perturbation: for $v \in C^1([0, T], \mathscr{G})$ satisfying v(0) = v(T) = 0 and $\varepsilon > 0$, let $e_{\varepsilon, v}(\cdot) \in C^1([0, T], G)$ the flow generated by εv :

$$\begin{cases} \frac{d}{dt} \boldsymbol{e}_{\varepsilon,v}(t) &= \varepsilon \dot{\boldsymbol{v}}(t) \cdot \boldsymbol{e}_{\varepsilon,v}(t) \\ \boldsymbol{e}_{\varepsilon,v}(0) &= \boldsymbol{e} \end{cases}$$

Definition

We say that $g \in \mathscr{S}(G)$ is a critical point of J if for all $v \in C^1([0, T], \mathscr{G})$ satisfying v(0) = v(T) = 0,

$$\frac{dJ}{d\varepsilon}|_{\varepsilon=0}g_{\varepsilon,v}=0$$
 where $g_{\varepsilon,v}(t)=e_{\varepsilon,v}(t)g(t).$

On the space $\mathscr{S}(G)$ of G-valued semimartingales define

$$J(\xi) = \frac{1}{2} \mathbb{E} \left[\int_0^T \left\| \frac{D\xi}{dt} \right\|^2 dt \right].$$

Perturbation: for $v \in C^1([0, T], \mathscr{G})$ satisfying v(0) = v(T) = 0 and $\varepsilon > 0$, let $e_{\varepsilon, v}(\cdot) \in C^1([0, T], G)$ the flow generated by εv :

$$\begin{cases} \frac{d}{dt} \boldsymbol{e}_{\varepsilon, v}(t) = \varepsilon \dot{\boldsymbol{v}}(t) \cdot \boldsymbol{e}_{\varepsilon, v}(t) \\ \boldsymbol{e}_{\varepsilon, v}(0) = \boldsymbol{e} \end{cases}$$

Definition

We say that $g \in \mathscr{S}(G)$ is a critical point of J if for all $v \in C^1([0, T], \mathscr{G})$ satisfying v(0) = v(T) = 0,

$$rac{dJ}{darepsilon}igert_{arepsilon=0}g_{arepsilon,
u}=0 ext{ where } g_{arepsilon,
u}(t)=e_{arepsilon,
u}(t)g(t).$$

< ロ > < 同 > < 回 > < 回 >

С

Semi-martingales in a Lie group Stochastic Euler-Poincaré reduction Group of volume preserving diffeomorphisms Navier-Stokes and Camassa-Holm equations

Theorem

g is a critical point of J if and only if

$$\frac{du(t)}{dt} = -\mathrm{ad}^*_{\tilde{u}(t)}u(t) - K(u(t))$$

with

$$\tilde{u}(t) = u(t) - \frac{1}{2} \sum_{i \ge 1} \nabla_{H_i} H_i, \quad \langle \operatorname{ad}_u^* v, w \rangle = \langle v, \operatorname{ad}_u v \rangle$$

and $K : \mathscr{G} \to \mathscr{G}$ satisfies

$$\langle \mathcal{K}(u), v \rangle = -\left\langle u, \frac{1}{2} \sum_{i \geq 1} \nabla_{\mathrm{ad}_{V}H_{i}}H_{i} + \nabla_{H_{i}}\left(\mathrm{ad}_{v}(H_{i})\right) \right\rangle$$

Remark 1

If for all $i \ge 1$, $H_i = 0$, or $\nabla_u v = 0$ for all $u, v \in \mathcal{G}$, then K(u) = 0 and we get the standard Euler-Poincaré equation.

<ロ> <問> <問> < 回> < 回> 、

С

Semi-martingales in a Lie group Stochastic Euler-Poincaré reduction Group of volume preserving diffeomorphisms Navier-Stokes and Camassa-Holm equations

Theorem

g is a critical point of J if and only if

$$\frac{du(t)}{dt} = -\mathrm{ad}^*_{\tilde{u}(t)}u(t) - K(u(t))$$

with

$$\tilde{u}(t) = u(t) - \frac{1}{2} \sum_{i \ge 1} \nabla_{H_i} H_i, \quad \langle \operatorname{ad}_u^* v, w \rangle = \langle v, \operatorname{ad}_u v \rangle$$

and $K : \mathscr{G} \to \mathscr{G}$ satisfies

$$\langle \mathcal{K}(u), v \rangle = -\left\langle u, \frac{1}{2} \sum_{i \geq 1} \nabla_{\mathrm{ad}_{V}H_{i}}H_{i} + \nabla_{H_{i}}\left(\mathrm{ad}_{v}(H_{i})\right) \right\rangle$$

Remark 1

If for all $i \ge 1$, $H_i = 0$, or $\nabla_u v = 0$ for all $u, v \in \mathcal{G}$, then K(u) = 0 and we get the standard Euler-Poincaré equation.

・ロト ・回ト ・ヨト ・ヨト

э

Proposition

If for all $i \geq 1$, $\nabla_{H_i} H_i = 0$ then

$$K(u) = -\frac{1}{2}\sum_{i\geq 1} \nabla_{H_i} \cdot \nabla_{H_i} u + R(u, H_i)H_i.$$

In particular if (H_i) is an o.n.b. of \mathcal{G} then

$$\mathcal{K}(u) = -rac{1}{2}\Box u = -rac{1}{2}\Delta u + rac{1}{2}\mathrm{Ric}^{\sharp}u$$
 the Hodge Laplacian.

< ロ > < 同 > < 三 > < 三 > 、

Let

$$G_v^s = \{g: M \to M \text{ volume preserving bijection, such that } g, g^{-1} \in H^s\}.$$

Assume $s > 1 + \frac{\dim M}{2}$. Then G_V^s is a C^∞ smooth manifold. Lie algebra

$$\mathscr{G}_V^s = T_e G_V^s = \{X : H^s(M, TM), \pi(X) = e, \operatorname{div}(X) = 0\}.$$

Notice that $\pi(X) = e$ means that X is a vector field on M: $X(x) \in T_x M$. On \mathscr{G}_V^s consider the two scalar products

$$\langle X, Y \rangle^0 = \int_M \langle X(x), Y(x) \rangle \, dx$$

and

$$\langle X, Y \rangle^1 = \int_M \langle X(x), Y(x) \rangle \, dx + \int_M \langle \nabla X(x), \nabla Y(x) \rangle \, dx.$$

The Levi Civita connection on G_V^s is given by $\nabla_X^{0V}Y = P_e(\nabla_X^0Y)$ with ∇^0 the Levi Civita connection of $\langle \cdot, \cdot \rangle^0$ on G^s and P_e the orthogonal projection on \mathscr{G}_V^s :

 $H^{s}(TM) = \mathscr{G}^{s}_{V} \oplus dH^{s+1}(M).$

One can find $(H_i)_{i\geq 1}$ such that for all $i\geq 1$, $\nabla_{H_i}H_i=0$, $\operatorname{div}(H_i)=0$, and

$$\sum_{i\geq 1} H_i^2 f = \nu \Delta f, \quad f \in C^2(M).$$

Let

$$G_v^s = \{g: M \to M \text{ volume preserving bijection, such that } g, g^{-1} \in H^s\}.$$

Assume $s > 1 + \frac{\dim M}{2}$. Then G_V^s is a C^∞ smooth manifold. Lie algebra

$$\mathscr{G}_V^s = T_e G_V^s = \{X : H^s(M, TM), \pi(X) = e, \operatorname{div}(X) = 0\}.$$

Notice that $\pi(X) = e$ means that X is a vector field on M: $X(x) \in T_x M$. On \mathscr{G}_V^s consider the two scalar products

$$\langle X, Y \rangle^0 = \int_M \langle X(x), Y(x) \rangle \, dx$$

and

$$\langle X, Y \rangle^1 = \int_M \langle X(x), Y(x) \rangle \, dx + \int_M \langle \nabla X(x), \nabla Y(x) \rangle \, dx.$$

The Levi Civita connection on G_V^s is given by $\nabla_X^{0V} Y = P_e(\nabla_X^0 Y)$ with ∇^0 the Levi Civita connection of $\langle \cdot, \cdot \rangle^0$ on G^s and P_e the orthogonal projection on \mathscr{G}_V^s :

$$H^{s}(TM) = \mathscr{G}^{s}_{V} \oplus dH^{s+1}(M).$$

One can find $(H_i)_{i>1}$ such that for all $i \ge 1$, $\nabla_{H_i} H_i = 0$, div $(H_i) = 0$, and

$$\sum_{i\geq 1}H_i^2f=\nu\Delta f,\quad f\in C^2(M).$$

Let

$$G_v^s = \{g: M \to M \text{ volume preserving bijection, such that } g, g^{-1} \in H^s\}.$$

Assume $s > 1 + \frac{\dim M}{2}$. Then G_V^s is a C^∞ smooth manifold. Lie algebra

$$\mathscr{G}_V^s = T_e G_V^s = \{X : H^s(M, TM), \pi(X) = e, \operatorname{div}(X) = 0\}.$$

Notice that $\pi(X) = e$ means that X is a vector field on M: $X(x) \in T_x M$. On \mathscr{G}_V^s consider the two scalar products

$$\langle X, Y \rangle^0 = \int_M \langle X(x), Y(x) \rangle \, dx$$

and

$$\langle X, Y \rangle^1 = \int_M \langle X(x), Y(x) \rangle \, dx + \int_M \langle \nabla X(x), \nabla Y(x) \rangle \, dx.$$

The Levi Civita connection on G_V^s is given by $\nabla_X^{0V} Y = P_e(\nabla_X^0 Y)$ with ∇^0 the Levi Civita connection of $\langle \cdot, \cdot \rangle^0$ on G^s and P_e the orthogonal projection on \mathscr{G}_V^s :

$$H^{s}(TM) = \mathscr{G}^{s}_{V} \oplus dH^{s+1}(M).$$

One can find $(H_i)_{i\geq 1}$ such that for all $i\geq 1$, $\nabla_{H_i}H_i=0$, $\operatorname{div}(H_i)=0$, and

$$\sum_{i\geq 1}H_i^2f=\nu\Delta f,\quad f\in C^2(M).$$

Corollary

(1) g is a critical point of $J^{\langle \cdot, \cdot \rangle^0}$ if and only if u solves Navier-Stokes equation

$$\begin{cases} \frac{\partial u}{\partial t} &= -\nabla_u u + \frac{\nu}{2} \Delta u - \nabla p \\ \operatorname{div} u &= 0 \end{cases}$$

(2) Assume $M = \mathbb{T}^2$ the 2-dimensional torus. Then g is a critical point of $J^{\langle \cdot, \cdot \rangle^1}$ if and only if u solves Camassa-Holm equation

$$\begin{cases} \frac{\partial u}{\partial t} &= -\nabla_u v - \sum_{j=1}^2 \nabla_{v_j} u_j + \frac{\nu}{2} \Delta v - \nabla p \\ v &= u - \Delta u \\ \operatorname{div} u &= 0 \end{cases}$$

For the proof, use Itô formula and compute in different situations $ad_v^*(u)$ and K(u).

Corollary

(1) g is a critical point of $J^{\langle \cdot, \cdot \rangle^0}$ if and only if u solves Navier-Stokes equation

$$\begin{cases} \frac{\partial u}{\partial t} &= -\nabla_u u + \frac{\nu}{2} \Delta u - \nabla p \\ \operatorname{div} u &= 0 \end{cases}$$

(2) Assume $M = \mathbb{T}^2$ the 2-dimensional torus. Then *g* is a critical point of $J^{\langle \cdot, \cdot \rangle^1}$ if and only if *u* solves Camassa-Holm equation

$$\begin{cases} \frac{\partial u}{\partial t} &= -\nabla_u v - \sum_{j=1}^2 \nabla_{v_j} u_j + \frac{\nu}{2} \Delta v - \nabla p \\ v &= u - \Delta u \\ \operatorname{div} u &= 0 \end{cases}$$

For the proof, use Itô formula and compute in different situations $ad_v^*(u)$ and K(u).

< ロ > < 同 > < 回 > < 回 >

Corollary

(1) g is a critical point of $J^{\langle \cdot, \cdot \rangle^0}$ if and only if u solves Navier-Stokes equation

$$\begin{cases} \frac{\partial u}{\partial t} &= -\nabla_u u + \frac{\nu}{2} \Delta u - \nabla p \\ \operatorname{div} u &= 0 \end{cases}$$

(2) Assume $M = \mathbb{T}^2$ the 2-dimensional torus. Then *g* is a critical point of $J^{\langle \cdot, \cdot \rangle^1}$ if and only if *u* solves Camassa-Holm equation

$$\begin{cases} \frac{\partial u}{\partial t} &= -\nabla_u v - \sum_{j=1}^2 \nabla_{v_j} u_j + \frac{\nu}{2} \Delta v - \nabla p \\ v &= u - \Delta u \\ \operatorname{div} u &= 0 \end{cases}$$

For the proof, use Itô formula and compute in different situations $ad_v^*(u)$ and K(u).

< ロ > < 同 > < 回 > < 回 >